ME 115(a): Homework #3

(Due Friday Feb. 19, 2015)

Problem 1: (20 points) Do Problem 6(a,b,d,e) in Chapter 2 of the MLS text.

Problem 2: (15 points) Do Problem 11(a,b) in Chapter 2 of the MLS text.

Problem 3: (10 points) Do Problem 7 in Chapter 2 of the MLS text.

Problem 4: (15 points) Consider 2×2 complex matrices of the form:

$$M = \begin{bmatrix} z & w \\ -w^* & z^* \end{bmatrix} = \begin{bmatrix} (a+ib) & (c+id) \\ -(c-id) & (a-ib) \end{bmatrix}$$

where:

$$det(M) = zz^* + ww^* = 1$$

and $z, w \in \mathbb{C}$, and $*$ denotes complex conjugation. Such matrices form a matrix group termed the "special unitary matrices" of dimension 2, $SU(2)$.

- **Part (a):** Show that matrices:

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} \quad \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \quad \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix}$$

  form a basis for $SU(2)$. The element i is $\sqrt{-1}$. I.e., all elements of $SU(2)$ can be expressed as some combination of these elements. Next show that elements of $SU(2)$ are isomorphic to the unit quaternions. That is, there is a one-to-one correspondence between each element of $SU(2)$ and a unit quaternion.

- **Part (b):** Show that the special unitary representation of a rotation in terms of z-y-x Euler Angles can be computed as :

$$\begin{bmatrix} \cos\frac{\psi}{2} & i\sin\frac{\psi}{2} \\ i\sin\frac{\psi}{2} & \cos\frac{\psi}{2} \end{bmatrix} \begin{bmatrix} \cos\frac{\phi}{2} & \sin\frac{\phi}{2} \\ -\sin\frac{\phi}{2} & \cos\frac{\phi}{2} \end{bmatrix} \begin{bmatrix} e^{i\frac{\gamma}{2}} & 0 \\ 0 & e^{-i\frac{\gamma}{2}} \end{bmatrix}$$

  where ψ, ϕ, and γ are respectively the rotations about the z, y, and x axes.

Problem 4: (10 points)

- **Part (a)** Derive a formula for the rotation matrix corresponding to z-y-x Euler angles (we derived the z-y-z angles in class).

- **Part (b)** Given a matrix $R \in SO(3)$, derive formulas to compute the z-y-x Euler angle values from the given matrix R.